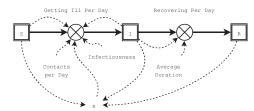
System Dynamics with MCSim

A Facilitated Systems Ouick Reference

An Example: the SIR Model

This simple model of a disease epidemic has three state variables, S, I, and R, representing the number of susceptible, infectious, and recovered (and thus immune) people in the population.



Susceptible people become ill and thus infectious by contacting an infectious person. The number getting ill per day is the product of the total number of susceptible people, the number of contacts they have per day with infectious people, and the probability that a contact results in disease. The probability of a contact being with an infectious person is the ratio of the number of infectious people to the total population. There is no incubation period.

The disease has a fixed average duration. The number of people recovering per day is the number of infectious people divided by the average duration.

A stock and flow diagram can be used to help design a system dynamics model and to communicate its structure to others. In the diagram, rectangles represent state variables (stocks), pipes with stylized valves represent flows between state variables, and dotted lines represent information flows. Clouds at the start or end of flows indicate system boundaries.

This work is licensed under the Creative Commons Attribution-NonCommercial-ShareAlike 2.5 License, To view a copy of this license, visit http://creativecommons.org/licenses/by-nc-sa/2.5/ or send a letter to Creative Commons, 543 Howard Street, 5th Floor, San Francisco, California, 94105, USA.

```
Model Listing: sir.model
States = {
  S, # No of susceptibles
      # No of infectious
      # No of recovered
Outputs = {
  Getting Ill PD,
  Recovering PD,
  Reproduction Rate,
};
Initial S =
                 9999.0:
Initial I =
                    1.0:
Initial R =
                    0.0:
Contacts PD =
                    4.0:
Infectiousness =
                    0.25:
Average Duration = 4.0;
Initialize{
  S = Initial S;
  I = Initial I:
  R = Initial R;
Dynamics{
  N = S + I + R;
  Getting Ill PD =
    Contacts PD * (I / N)
    * Infectiousness * S:
  Recovering PD =
    I / Average Duration;
  dt(S) = -Getting Ill PD;
  dt(I) = Getting \overline{Ill} \overline{PD}
    - Recovering PD;
  dt(R) = Recovering PD;
CalcOutputs{
  Reproduction Rate =
    Contacts PD *
    Infectiousness *
    Average Duration * (S/N);
```

```
Simulation File: sir.test01.in
Integrate(Lsodes, 1.0e-6, 1.0e-6, 0);
OutputFile("sir.test01.out");
StartTime(0.0);
Initial S = 9999.0;
Infectiousness = 0.25:
Simulation { # Base
Contacts PD = 3.0:
Average Duration = 4.0;
PrintStep(I,0.0,200.0,1.0);
PrintStep(Getting Ill PD, 0.0, 200.0,
 1.0):
Simulation { # Safe
Contacts PD = 1.0;
Average \overline{D}uration = 1.0;
PrintStep(I,0.0,200.0,1.0);
PrintStep(Getting Ill PD, 0.0, 200.0,
 1.0);
Simulation { # Scary
Contacts PD = 5.0;
Average \overline{D}uration = 7.0;
  <method>);
```

```
Simulation File Commands
Integrate(Lsodes, <rtol>, <atol>,
<rtol>: rel. error tolerance at each step
<atol>: abs. error tolerance at each step
<method>: 0 for non-stiff, 1 for stiff systems
Integrate(Euler, <time-step>, 0,
 0);
Print(<identifier1>,
 <identifier2>, ..., <time1>,
 <time2>, ...);
PrintStep(<identifier>, <start-</pre>
 time>, <end-time>, <time-step>);
```

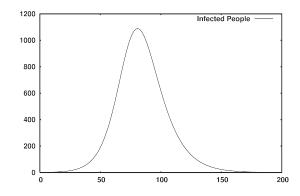
Model Execution

```
Cygwin:
$ makemcsims sir.model
$ ./mcsimstd.sir sir.test01.in
Other Environments:
$ makemcsim sir.model
$ ./mcsimstd.sir sir.test01.in
Model Output
$ less sir.test01.out
Results of Simulation 1
```

```
Time I
                  Getting Ill PD
0
      1
                  0.749925
1
      1.64854
                  1.23616
2
                  2.03735
      2.71743
      4.47868
                  3.35692
```

Gnuplot

qnuplot> plot 'sir.test01.out' index 4 using 1:2 title 'Infected People' with lines

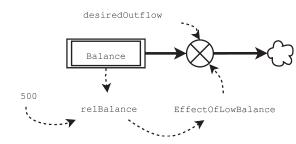


Facilitated Systems

making sense of tough problems together

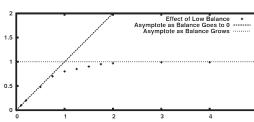
http://facilitatedsystems.com/ bill harris@facilitatedsystems.com +1 425 374-1845 ©2006 Facilitated Systems

Nonlinearities



Copy the italicized Inline code, substituting your own expressions for the bold text.

```
States = {Balance};
Initialize {Balance = 1000.0;}
desiredOutflow = 100.0;
Dynamics {
Inline(
#include <qsl/qsl errno.h>
#include <qsl/qsl spline.h>
gsl interp accel *accel ptr;
gsl spline *spline ptr;
int npts = 13;
double x \ array[13] = \{0.0, 0.1,
0.2, 0.5, 0.75, 1.0, 1.25, 1.5,
1.75, 2.0, 3.0, 4.0, 5.0};
double y = array[13] = \{0.0, 0.1,
0.2, 0.48, 0.7, 0.8, 0.85, 0.9,
0.95, 0.97, 0.99, 0.99, 1.0};
accel ptr =
gsl interp accel alloc ();
spline ptr = qsl spline alloc
(qsl interp akima, npts);
gsl spline init (spline ptr,
x_array, y_array, npts);
```



```
EffectOfLowBalance = 0.0:
relBalance = Balance / 500.0;
Inline(
EffectOfLowBalance =
gsl spline eval (spline ptr,
relBalance, accel ptr);
dt(Balance) = -desiredOutflow *
 EffectOfLowBalance;}
```

Inline Variable Names

To use the output variable **foo** in an inline section, call it rgModelVars[ID_foo]. For an input, use vrgInputs[ID foo]. For the calculated derivative of a state variable, use rgDerivs[ID_foo]. For a dynamic variable or a global parameter, use **foo**.

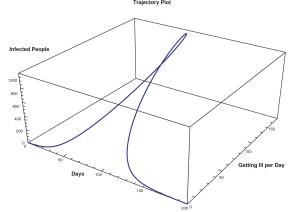
The following script will load an MCSim output file containing multiple experiments if each experiment has the same outputs. Note that J commands can only be one line long, so you must type what are shown as indented continuation lines all on one line.

```
require 'convert csv misc plot'
require 'statfns strings'
data =: 0 & ". @: detab"1
simcount =: +/@:(,@:-.)@:(-:"0
 1&0)@:('Simulation'&(I.@E.)"1@:>)
vc0 =: 2 & {
vc1 =: TAB & chop @: >
varcount =: <: @: # @: vc1 @: vc0
datalength =: (<:^:5) @: (# %
 simcount)
rs =: 3 : 0
d =: readcsv y
sc =: simcount d
vc =: varcount d
dl =: datalength d
dselect = . (sc * dl + 5) $ (3#0),
 (dl # 1), 2 # 0
D1=. data > dselect # d
(sc, dl, vc+1)& $ @: ,D1
qd =: 4 : 0
'i i' = . x
```

```
(i & {"1) @: (j & {) y
vn =: 3 : 0
baseindex =. +/\setminus sc # dl + 5
offsetindex =. (dl + 3) - \sim
 baseindex
(chop ": i. >: vc), ,"2 ;: >
  offsetindex { d
```

Run the script, and then use the following commands to analyze the data:

```
D=:rs fselect'' NB. data => D
                NB. variable names
(1 2) gd D NB. get data for the
 1st variable in the 2nd experiment
plot ((0 0)&gd;(1 2)&gd) D NB.
 plot that data vs. time
plot ((0 0)&qd;(2 4)&qd;(1 4)&qd)D
 NB. trajectory plot: 2nd and 1st
 variables, 4th experiment vs .time
cpd=: 3 1 5 5 1 [ ad=: 4 1 7 1 7
NB. The left-most 1 in 1&{"1 below
 selects the column for the
 variable to plot, starting with 0
 for the time column.
'type stick; title "Max Infected";
 pensize 7' plot cpd;ad;(max"1)
 1&{"1 D NB. peak infection across
 all five experiments
'type stick; title "Peak Time";
 pensize 7' plot cpd;ad;({."1
 (<<1){d}{-(i."1 0)(max"1)}
 1&{"1 d=.D NB. time of peak
 infection
```



```
Software
Programs:
MCSim (5.1.beta or later)
bash, gcc, make, GNU Scientific Library
man, texinfo
Gnuplot
Emacs or Vim
RCS, CVS, or Subversion
Dia; OpenOffice.org, LaTeX, or DocBook
Windows Sources:
http://cygwin.com/
http://gnu.org/software/emacs/windows/
  ntemacs.html
http://www.componentsoftware.com/csrcs/
http://miktex.org/
http://e-novative.info/software/ede.php
Mac OS X Sources:
http://fink.sourceforge.net/
Linux Sources:
$ apt-get ...
```

Common Sources:

http://fredomatic.free.fr/

http://gnuplot.info/

http://jsoftware.com/

http://gnu.org/software/emacs/

http://vim.org/

http://www.gnome.org/projects/dia/

http://openoffice.org/

http://ctan.org/

http://wiki.docbook.org/

References

Bois, Frédéric Y. and Don R. Maszle. 2004. MCSim: A Monte Carlo Simulation Program. User's Manual, software version 5.0.0.

Sterman, John D. 2000. Business Dynamics: *Systems Thinking and Modeling for a Complex* World. Boston: McGraw-Hill.

Making Sense With Facilitated Systems

http://facilitatedsystems.com/weblog/